## MATH 5061 Solutions to Problem Set $1^1$

1. Show that  $\mathbb{S}^2$  and  $\mathbb{CP}^1$  are diffeomorphic by constructing an explicit diffeomorphism between them. Solution:

Construct the map  $f: \mathbb{S}^2 \to \mathbb{CP}^1$  by

$$f(x_1, x_2, x_3) := \begin{cases} [\frac{x_1 + ix_2}{1 - x_3}, 1], & x_3 \neq 1\\ [1, \frac{x_1 - ix_2}{1 + x_3}], & x_3 \neq -1 \end{cases}$$

We need to verify f is well-defined when  $x_3 \neq 1, -1$ . Indeed, we have (Note  $x_1 + ix_2 \neq 0$ .)

$$\left[\frac{x_1 + ix_2}{1 - x_3}, 1\right] = \left[1, \frac{1 - x_3}{x_1 + ix_2}\right] = \left[1, \frac{(1 - x_3)(x_1 - ix_2)}{x_1^2 + x_2^2}\right] = \left[1, \frac{x_1 - ix_2}{1 + x_3}\right]$$

which shows f is well-defined.

Now let's show f is a diffeomorphism.

Let  $(U_1, \phi_1), (U_2, \phi_2)$  be the two charts on  $\mathbb{S}^2$  defined as

$$U_1 = \mathbb{S}^2 \setminus \{(0,0,1)\}, \phi_1(x_1, x_2, x_3) = (\frac{x_1}{1-x_3}, \frac{x_2}{1-x_3})$$
$$U_2 = \mathbb{S}^2 \setminus \{(0,0,-1)\}, \phi_2(x_1, x_2, x_3) = (\frac{x_1}{1+x_3}, \frac{x_2}{1+x_3})$$

Let  $(V_1, \varphi_1), (V_2, \varphi_2)$  be the two charts on  $\mathbb{CP}^1$  defined by

$$V_1 = \mathbb{CP}^1 \setminus \{[1,0]\}, \varphi_1([z_1, z_2]) = \frac{z_1}{z_2}$$
$$V_2 = \mathbb{CP}^1 \setminus \{[0,1]\}, \varphi_2([z_1, z_2]) = \frac{z_2}{z_1}$$

So for  $p \in U_1$ , f has the form under the chart  $(U_1, \phi_1)$  and  $(V_1, \varphi_1)$  as following

$$\varphi_1 \circ f \circ \phi_1^{-1}(u_1, u_2) = u_1 + iu_2$$

which is a smooth function.

For  $p \in U_2$ , we have

$$\varphi_2 \circ f \circ \phi_2(u_1, u_2) = u_1 - iu_2$$

which is also smooth.

Hence f is a diffeomorphism.

 $<sup>^{1}\</sup>mathrm{Last}$  revised on March 5, 2024

2. Prove that the tangent bundle TM is always orientable as a manifold.

## Solution:

Let  $\mathcal{A} = \{(U_i, \phi_i)\}_{i \in I}$  be an atlas of  $M^m$ . Then we let

$$\tilde{A} := \{ (TU_i, \tilde{\phi}_i) : i \in I \} \text{ with } \tilde{\phi}_i(p, v) = (\phi(p), d\phi_p(v)) \in \phi(U_i) \times \mathbb{R}^m$$

The transition maps between  $(TU_i, \tilde{\phi}_i), (TU_j, \tilde{\phi}_j)$  is

$$\Phi_{ij}(x,w) = (\phi_j \circ \phi_i^{-1}(x), d(\phi_j \circ \phi_i^{-1})_x(w))$$

Note that  $d(\phi_j \circ \phi_i^{-1})_x$  is linear, so the Jacobian matrix is just itself. Hence

$$d\Phi_{ij}(x,w) = \begin{bmatrix} d\left(\phi_j \circ \phi_i^{-1}(x)\right) & 0\\ 0 & d\left(\phi_j \circ \phi_i^{-1}(x)\right) \end{bmatrix}$$

Hence  $\det(d(\Phi_{ij})) = \left[d(\phi_j \circ \phi_i^{-1}(x))\right]^2 > 0$  since  $d(\phi_j \circ \phi_i^{-1}(x))$  non-degenerate. This means all the transition maps are orientation-preserving. Hence TM is

This means all the transition maps are orientation-preserving. Hence TM is orientable.

3. Prove Jacobi identity: [X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = 0 for any  $X, Y, Z \in \Gamma(TM)$ . Solution:

For any  $f \in C^{\infty}(M)$ , we directly compute,

$$[X, [Y, Z]]f = X([Y, Z]f) - [Y, Z](Xf)$$
  
=  $X(YZf - ZYf) - YZXf + ZYXf$   
=  $XYZf - YZXf + XZYf - ZYXf$ 

Similarly

$$\begin{split} &[Y,[Z,X]]f = YZXf - ZXYf + YXZf - XZYf \\ &[Z,[X,Y]]f = ZXYf - XYZf + ZYXf - YXZf \end{split}$$

Adding them up

$$\begin{split} & [X,[Y,Z]] + [Y,[Z,X]] + [Z,[X,Y]]f \\ & = (XYZ + YZX + ZXY)f - (YZX + ZXY + XYZ)f \\ & (XZY + YXZ + ZYX)f - (ZYX + XZY + YXZ)f \\ & = 0 \end{split}$$

Hence

$$[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = 0$$

4. Let  $\alpha$  be a (0,q)-tensor on  $M, X, Y_1, \cdots, Y_q \in \Gamma(TM)$  be vector fields. Show that

$$(\mathcal{L}_X \alpha)(Y_1, \cdots, Y_q) = X(\alpha(Y_1, \cdots, Y_q)) - \sum_{i=1}^q \alpha(Y_1, \cdots, Y_{i-1}, [X, Y_i], Y_{i+1}, \cdots, Y_q).$$

## Solution:

By definition of pull-back, we have

$$(\phi_t^*\alpha)(Y_1,\cdots,Y_q)(x) = \alpha_{\phi_t(x)}(\phi_{t*}Y_1,\cdots,\phi_{t*}Y_q)$$

with  $x \in M$  where  $\phi_t$  is the flow generated by X. So

$$\begin{aligned} (\mathcal{L}_{X}\alpha)(Y_{1},\cdots,Y_{q})(x) \\ &= \lim_{t \to 0} \frac{1}{t} \left( (\phi_{t}^{*}\alpha) \left(Y_{1},\cdots,Y_{q}\right)(x) - \alpha_{x}(Y_{1},\cdots,Y_{q}) \right) \\ &= \lim_{t \to 0} \frac{1}{t} \left( \alpha_{\phi_{t}(x)}(\phi_{t*}Y_{1},\cdots,\phi_{t*}Y_{q}) - \alpha_{x}(\phi_{t*}Y_{1},\cdots,\phi_{t*}Y_{q}) \right) \\ &+ \sum_{i=1}^{q} \lim_{t \to 0} \frac{1}{t} \left[ \alpha_{x}(\phi_{t*}Y_{1},\cdots,\phi_{t*}Y_{i-1},\phi_{t*}Y_{i},Y_{i+1},\cdots,Y_{q}) \right. \\ &- \alpha_{x}(\phi_{t*}Y_{1},\cdots,\phi_{t*}Y_{i-1},Y_{i},Y_{i+1},\cdots,Y_{q}) \right] \\ &= X(\alpha(Y_{1},\cdots,Y_{q}))(x) + \sum_{i=1}^{q} \alpha_{x}(Y_{1},\cdots,Y_{i-1},\mathcal{L}_{X}Y_{i},Y_{i+1},\cdots,Y_{q}) \\ &= X(\alpha(Y_{1},\cdots,Y_{q}))(x) - \sum_{i=1}^{q} \alpha_{x}(Y_{1},\cdots,Y_{i-1},[X,Y_{i}],Y_{i+1},\cdots,Y_{q}) \end{aligned}$$

Since the above identity holds for all  $x \in M$ , we have

$$(\mathcal{L}_X \alpha)(Y_1, \cdots, Y_q) = X(\alpha(Y_1, \cdots, Y_q)) - \sum_{i=1}^q \alpha(Y_1, \cdots, Y_{i-1}, [X, Y_i], Y_{i+1}, \cdots, Y_q)$$